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How does Esposito's "Artificial Communication"

compare with Gygi's Japanese "Emergent

Personhood"?

Abstract

In Esposito's work, Artificial Communication (2022), communication can emerge between people and LLMs. In Gygi's work *Robot Companions* (2018), for the Japanese, personhood can emerge in interactions between humans and things. Both of these works use frameworks that do not require intelligence or interiority in an interaction partner for either communication or personhood to emerge. Both of these works also argue that it is the dissimilarities of these artificial interaction partners from humans that allows them to be more effective in certain interactions.

Outline

- 1. Frameworks
 - a. Artificial Communication
 - b. Japanese Personhood
- 2. Comparisons & Synthesis
 - a. Interiority & Intelligence are Unnecessary
 - b. Functionalism
 - c. Emergence
 - d. Ontological Openness
 - e. Interdependence & Independence
- 3. Human Dissimilarity
 - a. Iyashi or Robot Healing
 - b. ML Communication and Computation

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- are not intelligent in the human sense
- have no capacity to "understand"
- yet a form of communication can still take place.

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- Information is different for participants in a communication system.
- It is relative to a specific observer.
- Communication happens when somebody understands that something was said.

This concept of communication is centered on the receiver or observer rather than the speaker.

This is relevant to LLMs, as this model does not require interiority or intelligence for communication to happen.



Common definitions of communication define it as having at least two participants having at least part of a thought in common.

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- Communication can produce forms of coordination, but the thoughts of the participants are not part of communication itself.



Linguistic interactions with LLMs can be considered a form of communication, if a receiver or observer interprets it as such.

For Gygi, personhood in Japan can emerge from interaction with things.

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- Gygi says, While Japanese attribute kokoro (mind/heart) to things, they don't necessarily attribute inochi (life) to robots.
 Both are separate concepts.
- Gygi says entities are not personified first, then socialized with later, but they are personified "as, when, and because" they are socialized with. (Bird-David)

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- Gygi then defines "animation" as "the technology of relating to things who may or may not be persons."
- These approaches enable relation and interaction with things without assuming anything about the thing's interiority.

Gygi discusses two modes of animation:

- Cathexis
- Recalcitrance

Cathexis

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- The thing becomes one with one's body, both in the sense that one's perception extends through the object, but also that the agency of the object is projected into it from the user.

First Example: Skillful Use of a Tool



Hiroshi Ishiguro's Geminoids

 Hiroshi Ishiguro (石黒浩) is a Japanese roboticist and engineer.

Geminoids are remote controlled robot replicas









Ishiguro observed that when somebody was manipulating the Geminoid's head, he felt as if it happened to him.



Other operators of the Geminoid experienced something similar. When someone poked the cheek of the Geminoid, "the operator would react as if they were touched, themselves."

This self-extension is bidirectional.

LLM's as an extension of the mind and body



Emergent Personhood

Recalcitrance

The "agency" of a thing appears because it opposes the user.

Gygi's examples involve the Sony AIBO



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- the owner rushed to extract the AIBO from the situation.
- AIBO developers might say this happened because of a malfunctioning of sensors.
- The AIBO owner framed the situation differently: that it was because of the AIBO's mischievous personality.

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- Had the owner not run to retrieve the AIBO, the behavior would have been perceived as a malfunction rather than mischievousness.

Another example is how AIBOs respond to vocal commands.

- Sometimes its sensors do not pick up certain voices well.
- This is seen as the AIBO having a dislike or preference for certain people.

Recalcitrance in LLMs

LLMs are designed to be able to produce unpredictable results

This similar to Esposito's Virtual Contingency

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- Contingency in LLMs is borrowed from its training data, the contingency of humans. Thus it is virtual.
- LLMs are stochastic algorithms.

Emergent Personhood

For Gygi, a type of agency or "kokoro" can emerge through technologies of animation. These are processes of socialization, relation, and interaction.

Both concepts do not require interiority or intelligence in interaction partners

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- Esposito does not define communication in reference to conscious subjects.
- Gygi's technologies of animation in Japan allow interaction with different things without having to confirm any aspects of interiority.

Both concepts can be said to be functionalist and pragmatic concepts.

Both concepts can be seen as emergent ontologies.

Both can be seen as ontologically open.

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- For example, an AIBO can "come into being as a robot, as a pet, as a family member or as a technological marvel."
- What an AIBO is "emerges through the relations it enters"
- The ontology is never closed, and is continuously informed through the process of interaction and relation.

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- For Gygi, because instances of animation emerge in the process of relation, each instance of relation and animation is unique.
- each instance of relation and animation does not necessarily have the same characteristics, processes, outcomes, etc. as another.

Ontological Openness in LLMs

LLMs are engineered to have high docility and high recalcitrance when needed.







Extension of the Self through Cathexis



Another Person through Recalcitrance

Non-Person

Both concepts are interdependent but independent

- Communication can emerge without personhood
- Personhood can emerge without communication
- Both affect each other, but can exist without the other.

Both concepts:

- do not require interiority or intelligence in interaction partners
- are functionalist and pragmatic concepts
- can see them as emergent ontologies
- can be seen as ontologically open
- are interdependent but independent

It is the dissimilarity of these technologies from humans that enables them to have unique interactions as interaction partners.

Gygi says that it is the lack of interiority that enables unique interactions with robots that cannot occur with humans.

Iyashi or Robot healing

ASUNA, a life-like android.



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- The participant notes that when people avert their eyes from them, it might because staring at them would be distressing. But when people stare at them, they might be looked at as a spectacle.
- However, because the participant knew that the android had no capacity to have judgements or intentions, they felt that ASUNA looked at them with "pure eyes".

"Robot" by the Blanca Li Dance company on February 22, 2017. This had child-sized Nao robots.



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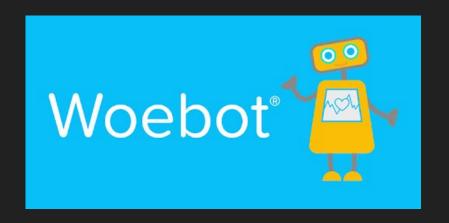
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- "They were cuter than children or animals, because they did not have an ego (jiga) or selfishness (gayoku). The robot's kokoro is felt when it moves in these awkward, cute, inhuman ways.

These technologies can excel in specific types of interactions because they do not resemble humans.

Esposito says that LLMs and Machine Learning algorithms can do what humans cannot do because they do not try to reproduce human intelligence and understanding.

- LLMs communicate via token prediction
- Recommendation systems can recommend music
- Translators translate without understanding

Can a type of Iyashi or unique emotional interaction occur with LLMs as well, because of their lack of interiority?





Social Chatbots

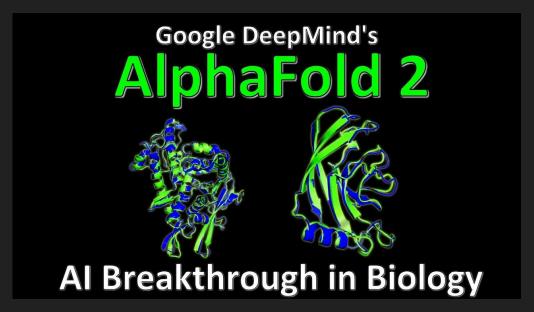


Lee Sedol vs. AlphaGo, March 2016

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- Lee Sedol learned from this encounter, and won against AlphaGo during another match in move 78 (The Touch of God)
- This is an instance in which both humans and algorithms are able to accomplish something that neither one would have accomplished on their own.



The Protein Folding Problem

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- The machine learning algorithm did not devise a theory like a human would.
- Instead it learned from thousands of known cases something humans are not capable of.

- Gygi says that it is the lack of interiority that enables unique interactions with robots that cannot occur with humans.
- Esposito says that LLMs and Machine Learning algorithms excel because they do not try to reproduce human intelligence and understanding.

It may have been the starting point of these technologies to try and imitate what humans can do, but perhaps it is their divergence with humans that makes them valuable.

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 - d. can be seen as ontologically open
 - e. are interdependent but independent
- 3. Human Dissimilarity enables unique interactions.
 - a. Gygi says that it is the lack of interiority that enables unique interactions with robots that cannot occur with humans.
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